## CSE Qualifying Exam, Fall 2023: Numerical Analysis

## Instructions:

- This is a CLOSED BOOK exam. No books or notes are allowed.
- No calculators, computers, phones, or internet usage allowed at any time during the exam (except for purposes of electronic proctoring, e.g., Honorlock).
- Answer three of the following four questions. All questions are graded on a scale of 10. If you answer all four, all answers will be graded and the three lowest scores will be used in computing your total.
- Show all your work and write in a readable way. Points will be awarded for correctness as well as clarity.
- Good luck!

- 1. Consider a sequence of  $m \times m$  symmetric matrices,  $\{A_1, A_2, \dots, \}$ . Let A be another symmetric matrix with distinct eigenvalues  $\lambda_1, \dots, \lambda_m$ , with,  $|\lambda_1| > |\lambda_2| > \dots > |\lambda_m|$  and corresponding (orthogonal) eigenvectors  $q_1, \dots, q_m$ .
  - (a) Let  $V^{(0)}$  be an  $m \times m$  matrix with linearly independent columns  $V_1^{(0)}, \dots, V_m^{(0)}$ . Define  $V^{(k)} = A_k V^{(k-1)}$  for  $k = 1, 2, \dots,$ . First consider the case when  $A_k := A$ , a constant matrix, for all k. Does the span of  $V_1^{(k)}, \dots, V_n^{(k)}$  converge with k, for each  $n \leq m$ ? If yes, give the rate of convergence in terms of the eigenvalues of A. (2 points)
  - (b) What is the numerical difficulty in carrying out the above iteration to obtain  $q_1, \dots, q_m$ ? Explain how this is resolved by normalizing  $V^{(k)}$  above with a QR factorization at each k. Discuss how  $q_1, \dots, q_m$  are then obtained. (2 points)
  - (c) Discuss how to obtain the eigenvalues of A from the above QR algorithm. How fast do the eigenvalues converge with iteration number k? (2 points)
  - (d) Given a symmetric A, construct a sequence  $\{A_k\}$  that is **not** constant and yields a faster rate of convergence for all eigenvalues and eigenvectors than (b) and (c). Show the rate of convergence. (2 points)
  - (e) Prove the backward stability of the algorithm in (d), stating any additional assumptions needed. (2 points)
- 2. For  $1 \leq p \leq \infty$ , define the condition number of a matrix  $\mathbf{A} \in \mathbb{R}^{m \times n}$  with respect to the *p*-norm as

$$\operatorname{cond}_{p}(\mathbf{A}) := \frac{\max_{\|x\|_{p}=1} \|\mathbf{A}\|_{p}}{\min_{\|x\|_{p}=1} \|\mathbf{A}\|_{p}}.$$
(1)

Here, the p norm is defined as

$$||x||_{p} = \begin{cases} (\sum_{i} |x_{i}|^{p})^{1/p}, & \text{for } p < \infty, \\ \max_{i} |x_{i}|, & \text{else.} \end{cases}$$
(2)

(a) [2.5pts] Show that for  $\mathbf{A} \in \mathbb{R}^{m \times n}$ ,

$$\operatorname{cond}_2\left(\mathbf{A}^T\mathbf{A}\right) = \operatorname{cond}_2(\mathbf{A})^2. \tag{3}$$

Hint: Remember to treat the case where the condition number is infinite.

- (b) [2.5pts] How would you use QR or Cholesky factorization to solve a system  $\mathbf{A}\mathbf{x} = \mathbf{b}$  for general but nonsingular  $\mathbf{A} \in \mathbb{R}^{m \times m}$ . Explain both approaches and reason why one of these approaches should generally be preferred over the other.
- (c) [2.5pts] Consider the diagonal matrix  $\mathbf{D} \in \mathbb{R}^{m \times m}$  of the form

$$\mathbf{D} = \begin{pmatrix} D_{11} & & \\ & \ddots & \\ & & D_{mm} \end{pmatrix}, \quad \forall 1 \le i \le m, D_{ii} > 0.$$
(4)

Compute  $\operatorname{cond}_{\infty}(\mathbf{D})$  and  $\operatorname{cond}_1(\mathbf{D})$ .

(d) [2.5pts] By means of an example, show that the result in (a) is not true when replacing  $\operatorname{cond}_2$  by a general  $\operatorname{cond}_p$ .

- 3. Remember that for a symmetric and positive-definite matrix  $\mathbf{A} \in \mathbb{R}^{m \times m}$ , its Cholesky factor  $\mathbf{L} = \operatorname{chol}(\mathbf{A})$  is the unique lower triangular matrix with positive diagonal that satisfies  $\mathbf{A} = \mathbf{L}\mathbf{L}^T$ . Define the Cholesky iteration as  $\mathbf{A}_0 = \mathbf{A}$ ,  $\mathbf{L}_{k+1} = \operatorname{chol}(\mathbf{A}_k)$  and  $\mathbf{A}_{k+1} = \mathbf{L}_k^T \mathbf{L}_k$ . In the following, assume that all eigenvalues of  $\mathbf{A}$  are distinct.
  - (a) [3.0] Show that for all  $k \ge 0$ ,  $\mathbf{A}_k$  has the same eigenvalues as  $\mathbf{A}_{k+1}$ . *Hint: Try to show that*  $\mathbf{A}_k = \mathbf{B}_k^{-1} \mathbf{A}_0 \mathbf{B}_k$  for  $\mathbf{B}_k = \mathbf{L}_1 \cdots \mathbf{L}_k$ .
  - (b) [3.0] Show that for  $\mathbf{b}_k$  the leading column of  $\mathbf{B}_k$ ,  $\mathbf{b}_{k+1}$  is a positive scalar multiple of  $\mathbf{A}\mathbf{b}_k$ .
  - (c) [3.0] Use (b) to show that  $\mathbf{b}_{k+1}$  converges to the eigenvector of the largest eigenvalue of  $\mathbf{A}$ .
  - (d) [1.0] Provide a similar algorithm that is applicable to nonsymmetric problems.
- 4. The following two subquestions are unrelated.
  - (a) [5pts] Let A be a symmetric positive definite matrix. Consider the conjugate gradient method for solving the system of equations Ax = b. Suppose the initial approximation  $x_0$  is such that the initial residual  $r_0 = b Ax_0$  is parallel to an eigenvector q of A with eigenvalue  $\mu$ , i.e.,  $r_0 = \gamma q$  where  $\gamma$  is a real number. Prove that the conjugate gradient method converges in one iteration.
  - (b) [5pts] Let A be a nonsymmetric and nonsingular matrix with real eigenvalues. If the Arnoldi algorithm is run on A with starting vector v for k steps, prove or disprove that the resulting  $k \times k$  upper Hessenberg matrix only has real eigenvalues.